MATH 226: Differential Equations



Class 28: November 16, 2022



Starting at 7 PM One Sheet of Notes

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Schedule This Week

- Today: Competition Model II Predator – Prey Model II
- Friday: Fragility of a Center Periodic Solutions and Limit Cycles

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Current Goal: Approximating Nonlinear Autonomous System With Linear System Near An Equilibrium Point

x' = F(x, y)y' = G(x, y)

$$F(x,y) \approx F(x^*,y^*) + F_x(x^*,y^*)(x-x^*) + F_y(x^*,y^*)(y-y^*)$$

$$G(x,y) \approx G(x^*,y^*) + G_x(x^*,y^*)(x-x^*) + G_y(x^*,y^*)(y-y^*)$$

But at Equilibrium Points, $F(x^*, y^*) = 0$, $G(x^*, y^*) = 0$ so

$$F(x,y) \approx F_x(x^*,y^*)(x-x^*) + F_y(x^*,y^*)(y-y^*)$$

$$G(x,y) \approx G_x(x^*,y^*)(x-x^*) + G_y(x^*,y^*)(y-y^*)$$

$$F(x,y) \approx F_x(x^*,y^*)(x-x^*) + F_y(x^*,y^*)(y-y^*)$$

$$G(x,y) \approx G_x(x^*,y^*)(x-x^*) + G_y(x^*,y^*)(y-y^*)$$

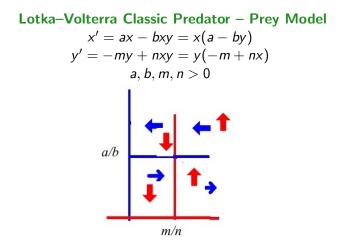
which we can write as

$$\begin{bmatrix} F_x(x^*, y^*) & F_y(x^*, y^*) \\ G_x(x^*, y^*) & G_y(x^*, y^*) \end{bmatrix} \begin{bmatrix} x - x^* \\ y - y^* \end{bmatrix}$$

or

$$J(x^*, y^*) \begin{bmatrix} x - x^* \\ y - y^* \end{bmatrix} = J(x^*, y^*) \begin{bmatrix} h \\ k \end{bmatrix}$$

J is called the Jacobi Matrix or Jacobian



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Predator - Prey Model with Logistic Prey Growth $x' = ax - px^2 - bxy$ y' = -my + nxya, b, m, n, p > 0a/b m/na/p

$$\frac{a}{p} > \frac{m}{n}$$
 so $n - pm > 0$

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Predator - Prey Model with Logistic Prey Growth

$$x' = ax - px^2 - bxy$$

$$y' = -my + nxy$$

$$a, b, m, n, p > 0$$

$$\begin{aligned} F(x,y) &= ax - px^2 - bxy & G(x,y) = -my + nx^2 \\ F_x(x,y) &= a - 2px - by & G_x(x,y) = ny \\ F_y(x,y) &= -bx & G_y(x,y) = -m + nx \end{aligned}$$

$$J(x,y) = \begin{bmatrix} F_x(x,y) & F_y(x,y) \\ G_x(x,y) & G_y(x,y) \end{bmatrix} = \begin{bmatrix} a - 2px - by & -bx \\ ny & nx - m \end{bmatrix}$$

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$$J(x,y) = \begin{bmatrix} a - 2px - by & -bx \\ ny & nx - m \end{bmatrix}$$

At Critical Point $(x^*, y^*) = (\frac{m}{n}, \frac{a}{b} - \frac{pm}{an})$:

$$J(x^*, y^*) = \begin{bmatrix} a - 2px - by & -bx \\ ny & nx - m \end{bmatrix}$$

$$A = J(x^*, y^*) = \begin{bmatrix} -\frac{pm}{n} & -\frac{bm}{n} \\ \frac{na-pm}{b} & 0 \end{bmatrix} = \begin{bmatrix} - & -1 \\ + & 0 \end{bmatrix}$$
so Trace(A) < 0 and Det(A) > 0

$$\lambda = \frac{\text{Trace}(A) \pm \sqrt{(\text{Trace}(A))^2 - 4\text{Det}(A)}}{2}$$

Real Parts of Eigenvalues Are Negative

For Classic Lotka–Volterra Model, set
$$p = 0$$

 $x' = ax - bxy$
 $y' = -my + nxy$
 $a, b, m, n, p > 0$

$$\begin{array}{ll} F(x,y) = ax - bxy & G(x,y) = -my + nx^2 \\ F_x(x,y) = a - by & G_x(x,y) = ny \\ F_y(x,y) = -bx & G_y(x,y) = -m + nx \end{array}$$

$$J(x,y) = \begin{bmatrix} F_x(x,y) & F_y(x,y) \\ G_x(x,y) & G_y(x,y) \end{bmatrix} = \begin{bmatrix} a - by & -bx \\ ny & nx - m \end{bmatrix}$$

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$$J(x,y) = \begin{bmatrix} a - by & -bx \\ ny & nx - m \end{bmatrix}$$

At Critical Point $(x^*, y^*) = (\frac{m}{n}, \frac{a}{b})$:

$$J(x^*, y^*) = \begin{bmatrix} a - by & -bx \\ ny & nx - m \end{bmatrix}$$

$$A = J(x^*, y^*) = \begin{bmatrix} 0 & -\frac{bm}{n} \\ \frac{na}{b} & 0 \end{bmatrix} = \begin{bmatrix} 0 & - \\ + & 0 \end{bmatrix}$$
so Trace(A) = 0 and Det(A) > 0

$$\lambda = \frac{Trace(A) \pm \sqrt{(Trace(A))^2 - 4Det(A)}}{2} = \pm \frac{\sqrt{-4Det(A)}}{2}$$

so $\lambda = \pm i\sqrt{det(A)}$. Eigenvalues are Pure Imaginary.

Jacobian Analysis of Classic Lotka – Volterra

$$F(x, y) = ax - bxy \qquad F_x = a - by \qquad F_y = -bx$$

$$G(x, y) = -my + nxy \qquad G_x = ny \qquad G_y = -m + nx$$

$$J(x, y) = \begin{pmatrix} a - by & -bx \\ ny & -m + nx \end{pmatrix}$$

$$J(0, 0) = \begin{pmatrix} a & 0 \\ 0 & -m \end{pmatrix}$$
Eigenvalue $\lambda = a$ with eigenvector $\mathbf{v} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
Eigenvalue $\lambda = -m$ with eigenvector $\mathbf{w} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

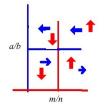


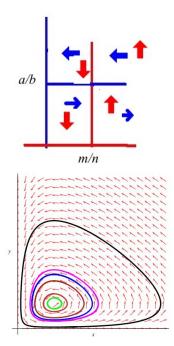
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Jacobian Analysis of Classic Lotka – Volterra

$$J(x,y) = \begin{pmatrix} a - by & -bx \\ ny & -m + nx \end{pmatrix}$$
$$J(\frac{m}{n}, \frac{a}{b}) = \begin{pmatrix} 0 & -\frac{bm}{n} \\ \frac{na}{b} & 0 \end{pmatrix}$$

Characteristic Equation: $\lambda^2 + am = 0$ so $\lambda = \pm i\sqrt{am}$ Solutions of Linear System will involve sin \sqrt{amt} , cos \sqrt{amt} . Linear System has center.





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More on Classic Lotka–Volterra

Linear System Near
$$\left(\frac{m}{n}, \frac{a}{b}\right)$$

 $u' = -\frac{bm}{n}v$
 $v' = \frac{an}{b}u$

$$\frac{v'}{u'} = \frac{an}{b}u \times \frac{n}{-bm}v = -\frac{an^2}{b^2m}\frac{u}{v}$$

Separate Variables:
$$b^2 m v v' = -an^2 u u u'$$

 $b^2 mv^2 = -an^2 u^2 + C$
 $an^2 u^2 + b^2 mv^2 = C$
Orbit is an ellipse.

Solutions are linear combinations of sin \sqrt{amt} and $\cos \sqrt{amt}$. These are periodic with average values $\frac{m}{n}$ (prey), $\frac{a}{b}$ (predator)

A Surprising Result

 $\begin{aligned} x' &= ax - bxy, y' = mxy - ny \text{ has Average Values } x^* &= \frac{m}{n}, y^* = \frac{a}{b} \\ \text{Suppose predators are birds and prey are mosquitos.} \\ \text{We spray insecticide to decrease further the number of mosquitos.} \\ \text{We now have} \\ x' &= ax - bxy - cx, y' = mxy - ny - d \text{ with } c > 0, d > 0 \\ x' &= x(a - c - by), y' = y(mx - (n + d). \end{aligned}$

New Equilibrium is
$$x^* = \frac{n+d}{m}, y^* = \frac{a-c}{b}$$

WE INCREASE THE AVERAGE NUMBER OF MOSQUITOS WHILE DECREASING THE AVERAGE NUMBER OF BIRDS!

Exact Orbits For Classic Lotka-Volterra

$$\frac{dy}{dx} = \frac{dy}{dt} / \frac{dx}{dt} = \frac{y(mx - n)}{x(a - by)} = \frac{y}{a - by} \frac{mx - n}{x}$$

$$\frac{dy}{dx} = \left(\frac{y}{a - by}\right) \left(\frac{mx - n}{x}\right)$$

Separate Variables and Integrate

$$\int \left(\frac{a-by}{y}\right) \, dy = \int \left(\frac{mx-n}{x}\right) \, dx$$

$$\int \left(\frac{a - by}{y}\right) dy = \int \left(\frac{mx - n}{x}\right) dx$$
$$\int \frac{a}{y} - b dy = \int m - \frac{n}{x} dx$$

$$a\ln y - by = mx - n\ln x + C$$

$$\ln y^{a} - by = mx - \ln x^{n} + C$$

Exponentiate each side:
$$e^{\ln y^{a} - by} = e^{mx - \ln x^{n} + C}$$

$$e^{\ln y^a}e^{-by}=e^{mx}e^{-\ln x^n}e^C$$

$$y^a e^{-by} = e^{mx} x^{-n} K$$

$$\left(y^{a}e^{-by}\right)\left(x^{n}e^{-mx}\right)=K$$

Let
$$u = y^a e^{-by}$$
 and $v = x^n e^{-mx}$

Then uv = K

We can graph

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$$f(x) = x^{n} e^{-mx}$$

$$f'(x) = x^{n-1} e^{-mx} (n - mx)$$

$$f''(x) = x^{n-2} e^{-mx} (m^{2}x^{2} - 2mnx + n^{2} - n)$$

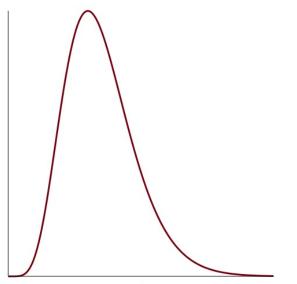
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$$f(x) \ge 0$$
, all x with $f(x) = 0$ if and only if $x = 0$.

▶ f'(x) > 0 if x < n/m and f'(x) < 0 for x > n/mHence there is a maximum at $x = \frac{n}{m}$.

Graph of
$$x^n e^{-mx} = \frac{x^n}{e^{mx}}, x \ge 0$$
 is

- Increasing and concave up on $[0, \frac{n-\sqrt{n}}{m}]$
- Increasing and concave down on $\left[\frac{n-\sqrt{n}}{m}, \frac{n}{m}\right]$.
- Decreasing and concave down on $\left[\frac{n}{m}, \frac{n+\sqrt{n}}{m}\right]$,
- Decreasing and concave up on $\left[\frac{n+\sqrt{n}}{m},\infty\right)$.
- ▶ $\lim_{x\to\infty} f(x) = 0$ (Repeated Use of l'Hôpital's Rule).

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Examples of Predator - Prey With Logistic Prey

$$a = 1, p = \frac{1}{2}, b = \frac{1}{2}, m = \frac{1}{4}, n = \frac{1}{2}$$
$$(x^*, y^*) = (\frac{1}{2}, \frac{3}{2})$$
$$J(\frac{1}{2}, \frac{3}{2}) = \begin{pmatrix} -\frac{1}{4} & -\frac{1}{4} \\ \frac{3}{4} & 0 \end{pmatrix}$$

Characteristic Polynomial: $\lambda^2 + \frac{1}{4}\lambda + \frac{3}{16}$ Eigenvalues: $\lambda = \frac{-1 \pm i \sqrt{11}}{8}$

Examples of Predator – Prey With Logistic Prey

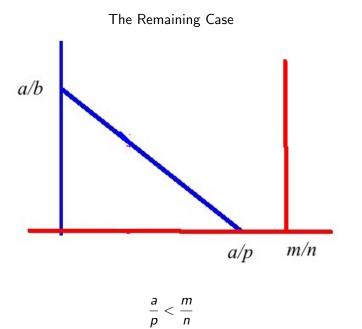
$$a = 16, p = 5/2, b = 7/8, m = 10, n = 2$$

 $(x^*, y^*) = (5, 4)$

$$J(5,4) = \begin{pmatrix} -\frac{25}{2} & -\frac{35}{8} \\ 8 & 0 \end{pmatrix}$$

Characteristic Polynomial: $\lambda^2 + \frac{25}{2}\lambda + 35$ Eigenvalues: $\lambda = \frac{-25\pm\sqrt{65}}{4}$ Both eigenvalues are negative.

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Simple Competition Model

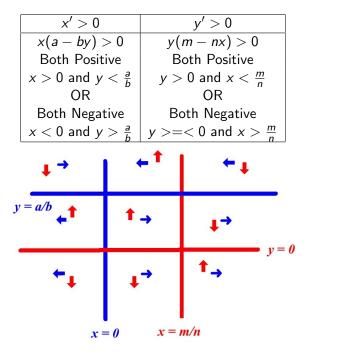
$$x' = ax - bxy = x(a - by) = F(x, y)$$

$$y' = my - nxy = y(m - nx) = G(x, y)$$

$$a, b, m, n > 0$$

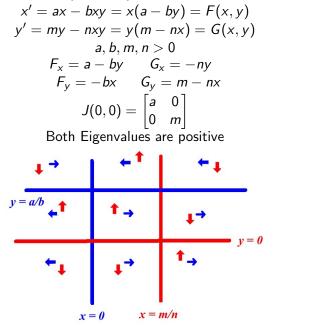
Search For Equilibrium Points x' = 0 at $x = 0, y = \frac{a}{b}$ y' = 0 at $y = 0, x = \frac{m}{n}$ Critical Points: (0,0) and $(\frac{m}{n}, \frac{a}{b})$: One Point Orbits x-axis is an orbit and y-axis is an orbit.

x' > 0	<i>y'</i> > 0
x(a-by)>0	y(m-nx)>0
Both Positive	Both Positive
$x > 0$ and $y < \frac{a}{b}$	$y > 0$ and $x < \frac{m}{n}$
OR	OR "
Both Negative	Both Negative
$x < 0$ and $y > \frac{a}{b}$	$y > = < 0$ and $x > \frac{m}{n}$

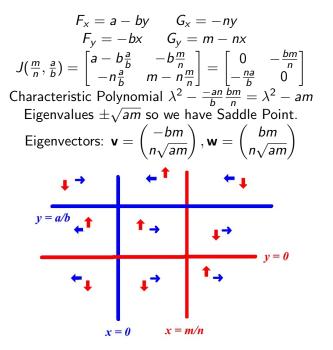


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Simple Competition Model



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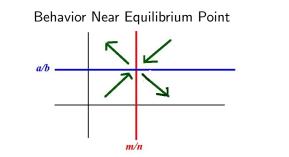


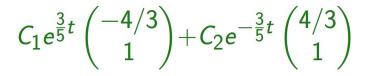
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A Specific Example: a = .9, b = .6, m = .4, n = .3Critical Point $(\frac{.4}{3}, \frac{.9}{6}) = (\frac{4}{3}, \frac{3}{2})$ $J() = \begin{vmatrix} 0 & -\frac{(.0)(.4)}{.3} \\ -\frac{.27}{6} & 0 \end{vmatrix} = \begin{vmatrix} 0 & -\frac{4}{5} \\ -\frac{9}{20} & 0 \end{vmatrix}$ Eigenvalue Eigenvector Solution $\lambda = \sqrt{36/100} = \frac{3}{5} \qquad \mathbf{v} = \begin{pmatrix} -4/3 \\ 1 \end{pmatrix} \qquad e^{\frac{3}{5}t} \mathbf{v}$ $\lambda = -\sqrt{(36/100} = -\frac{3}{5} \qquad \mathbf{w} = \begin{pmatrix} 4/3 \\ 1 \end{pmatrix} \qquad e^{-\frac{3}{5}t} \mathbf{w}$ General Solution of Linear System

$$C_1 e^{\frac{3}{5}t} \begin{pmatrix} -4/3\\ 1 \end{pmatrix} + C_2 e^{-\frac{3}{5}t} \begin{pmatrix} 4/3\\ 1 \end{pmatrix}$$

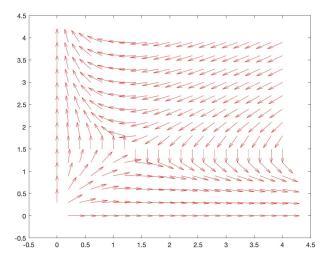
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Simple Model Of Competition x' = ax - bxyy' = my - nxya, b, m, n > 0

Each Species Grows Exponentially in Absence of Other.



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Simple Model x' = ax - bxyy' = my - nxya, b, m, n > 0

Each Species Grows **Exponentially** in Absence of Other.

More Realistic Model $x' = ax - px^2 - bxy$ $y' = my - qy^2 - nxy$ a, b, m, n > 0

Each Species Grows Logistically in Absence of Other.

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The Fragility of Being a Center Consider X' = AX with $A = \begin{pmatrix} 36 & 80 \\ -50 & -36 \end{pmatrix}$

Characteristic Polynomial: $\lambda^2 + 2704$ so eigenvalues are $\lambda = \pm 52i$ Suppose we replace 36 with $36 + \epsilon$ where ϵ is a small number.

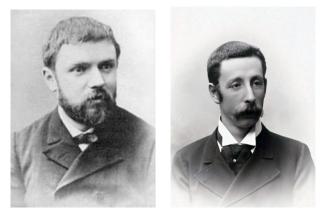
$$A = \begin{pmatrix} 36 + \epsilon & 80 \\ -50 & -36 \end{pmatrix}$$

Characteristic Polynomial: $\lambda^2 - \epsilon \lambda + 2704 - 36\epsilon$ so eigenvalues are $\lambda = \frac{\epsilon \pm \sqrt{\epsilon^2 + 144\epsilon - 10816}}{2}$

 ϵ small **positive** means real part $\frac{\epsilon}{2} > 0$: Spiral Source ϵ small **negative** means real part $\frac{\epsilon}{2} < 0$: Spiral Sink

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Poincaré – Bendixson Theorem



Henri Poincaré 1854 – 1912 Ivar Bendixson 1861 –1935

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