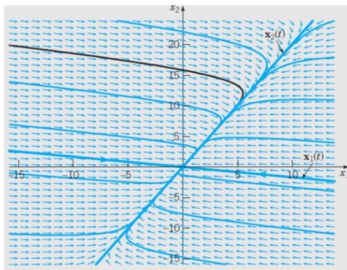


# MATH 226: Differential Equations

## Nodal Sources and Nodal Sinks



The pattern of trajectories in Figure is typical of all second order systems  $\mathbf{x}' = \mathbf{A}\mathbf{x}$  whose eigenvalues are real, different, and of the same sign. The origin is called a **node** for such a system.

Class 16: October 19, 2022



## MidTerm Feedback Form

"Nodal Links," A Maple print out on Unequal Roots  
*Unequal Roots.mw* in Handouts Folder for Maple  
File

Modernized MATLAB apps for Phase Planes  
(systems of differential equations) and Slope Fields  
(single differential equation)

URL at <https://www.mathworks.com/matlabcentral/fileexchange/91705-phase-plane-and-slope-field-apps>

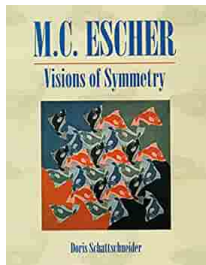
# Announcements

For Next Time, Work Through

## Complex Numbers

- Use the imaginary unit  $i$  to write complex numbers, and add, subtract, and multiply complex numbers.
- Find complex solutions of quadratic equations.
- Write the trigonometric forms of complex numbers.
- Find powers and  $n$ th roots of complex numbers.

Mathematician of the Week : **Doris Schattschneider**



October 19, 1939 –

Doris Schattschneider is an American mathematician who became professor of mathematics at the Moravian College. She was the first female editor of Mathematics Magazine and won many awards for her excellence in expository writing.

[Biography](#)

## Our Main Agenda

Solve  $\mathbf{X}' = \mathbf{A} \mathbf{X}$  where  $\mathbf{A}$  is an  $n \times n$  matrix of constants and  $\mathbf{X}$  is an  $n$ -dimensional vector of functions.

## Results So Far

*Theorem:* The set of solutions is a vector space.

We can find some solutions of the form  $e^{\lambda t} \vec{v}$  where  $\lambda$  is an eigenvalue of  $\mathbf{A}$  and  $\vec{v}$  is an associated eigenvector.

Distinct eigenvalues give rise to linearly independent solutions.

A linearly independent set of  $n$  solutions is a basis for the vector space.

## Outstanding Questions

What To Do If 0 is an eigenvalue?

How to handle complex eigenvalues.

How to find  $n$  linearly independent solutions to  $\mathbf{X}' = \mathbf{A} \mathbf{X}$  when there are not enough of the form  $e^{\lambda t} \vec{v}$ .

Today:

**Continue Study of Linear  
Homogeneous Systems  
With Constant Coefficients**

$$\mathbf{X}' = \mathbf{A} \mathbf{X}$$

**2 × 2 Case**

**With Real, Unequal Eigenvalues**

Theorem: If  $\lambda$  and  $\mu$  are distinct eigenvalues (real or complex) of a  $2 \times 2$  matrix  $A$  having corresponding eigenvectors  $\vec{v}$  and  $\vec{w}$ , then every solution of  $\mathbf{x}' = A \mathbf{x}$  is a linear combination of  $e^{\lambda t} \vec{v}$  and  $e^{\mu t} \vec{w}$ .

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

**Characteristic Polynomial** of  $A$  is  $\det(A - \lambda I) =$   
 $\lambda^2 - (a + d)\lambda + ad - bc$   
 $\lambda^2 - \text{Trace}(A) \lambda + \text{Det } A$

**Characteristic Equation:**  $\det(A - \lambda I) = 0$

**Eigenvalues** Are Roots of Characteristic Polynomial

$$\lambda = \frac{(a + d) \pm \sqrt{(a + d)^2 - 4(ad - bc)}}{2}$$

$$\lambda = \frac{(a + d) \pm \sqrt{(a - d)^2 + 4bc}}{2}$$



$$\lambda = \frac{(a + d) \pm \sqrt{(a - d)^2 + 4bc}}{2}$$

### Possibilities

2 Real Unequal Roots

2 Complex Roots

1 Real Double Root

### More About 2 Real Unequal Roots Case

$$\mathbf{x}' = A \mathbf{x}$$

The Origin (0,0) is an equilibrium and is called a **NODE**

## More About 2 Real Unequal Roots Case $\mathbf{x}' = A \mathbf{x}$

The Origin (0,0) is an equilibrium and is called a **NODE**

$\lambda_1, \lambda_2 < 0$       Node is Asymptotically Stable  
**NODAL SINK**

$\lambda_1, \lambda_2 > 0$       Node is Unstable  
**NODAL SOURCE**

Opposite Sign      Node is Unstable  
**SADDLE POINT**

Nodal Sink       $\begin{bmatrix} -7 & 3 \\ 2 & -2 \end{bmatrix}$        $\lambda = -1, -8$

Nodal Source       $\begin{bmatrix} 2 & 0 \\ -1 & 3 \end{bmatrix}$        $\lambda = 3, 2$

Saddle Point       $\begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix}$        $\lambda = 3, -1$

## ZERO AS AN EIGENVALUE

Example: Richardson Arms Race Model  
With Parallel Stable Lines

$$\begin{aligned}x' &= -mx + ay + r \\y' &= bx - ny + s\end{aligned}$$

$$\text{Slope of } \mathbf{L} = \frac{m}{a}$$

$$\text{Slope of } \mathbf{L}' = \frac{b}{n}$$

$$\text{Parallel if } \frac{m}{a} = \frac{b}{n}$$

$$A = \begin{bmatrix} -m & a \\ b & -n \end{bmatrix}$$

$$mn = ab \Leftrightarrow mn - ab = 0 \Leftrightarrow \det(A) = 0$$

$$\text{Characteristic Equation: } \lambda^2 + (m+n)\lambda + (mn - ab) = 0$$

$$\lambda^2 + (m+n)\lambda = 0$$

$$\lambda(\lambda + (m+n)) = 0 \Rightarrow \lambda = 0, \lambda = -(m+n)$$

## ZERO AS AN EIGENVALUE EXAMPLE

$$m = 3, a = 6, n = 8, b = 4$$

$$A = \begin{bmatrix} -3 & 6 \\ 4 & -8 \end{bmatrix}$$

$$\det \begin{bmatrix} -3 - \lambda & 6 \\ 4 & -8 - \lambda \end{bmatrix}$$

$$= (-3 - \lambda)(-8 - \lambda) - 24 = \lambda^2 + 11\lambda + 24 - 24$$

$$= \lambda^2 + 11\lambda = \lambda(\lambda + 11)$$

$$\lambda = 0, \lambda = -11$$

For  $\lambda = -11$  :

$$\begin{bmatrix} 8 & 6 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$4v_1 + 3v_2 = 0$$

$$\vec{v} = \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

For  $\lambda = 0$  :

$$\begin{bmatrix} -3 & 6 \\ 4 & -8 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-3w_1 + 6w_2 = 0$$

$$\vec{w} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\lambda = -11, \vec{v} = \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$\lambda = 0, \vec{v} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

General Solution To

$$x' = -3x + 6y$$

$$y' = 4x = 8y$$

$$\text{is } \mathbf{x} = C_1 e^{0t} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + C_2 e^{-11t} \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$x = 2C_1 - 3C_2 e^{-11t}$$

$$y = C_1 + 4C_2 e^{-11t}$$

Particular Solution:  $(x_0, y_0)$  at  $t = 0$

$$x_0 = 2C_1 - 3C_2$$

$$y_0 = C_1 + 4C_2$$

$$\begin{array}{l|l} 2C_1 - 3C_2 = x_0 & 8C_1 - 12C_2 = 4x_0 \\ -2C_1 - 8C_2 = -2y_0 & 3C_1 + 12C_2 = 3y_0 \\ \text{Add Equations} & \text{Add Equations} \\ -11C_2 = x_0 - 2y_0 & 11C_1 = 4x_0 + 3y_0 \end{array}$$

$$C_1 = \frac{4x_0 + 3y_0}{11}, \quad C_2 = \frac{-x_0 + 2y_0}{11}$$

$$x = 2 \left( \frac{4x_0 + 3y_0}{11} \right) - 3 \left( \frac{-x_0 + 2y_0}{11} \right) e^{-11t}$$

$$y = \frac{4x_0 + 3y_0}{11} + 4 \left( \frac{-x_0 + 2y_0}{11} \right) e^{-11t}$$

# Next Time

## Complex Eigenvalues

