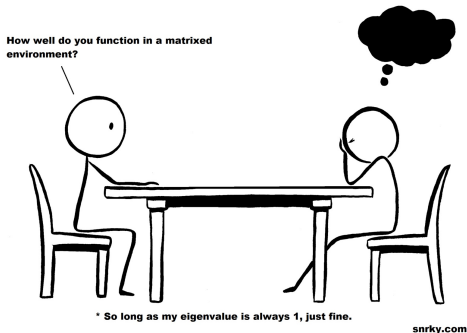


MATH 226 Differential Equations



Class 11: October 5, 2022



Assignment 8

Notes on Sample Exam 1

Project 1 Peer and Self Evaluations

Announcements

- ▶ First Team Projects Due Tomorrow
- ▶ Exam 1
 - ▶ Wednesday, October 12
 - ▶ 7 PM - ? (No Time Limit)
 - ▶ No Calculators, Books, Notes, Smart Phones, etc.
 - ▶ Focus on Material in Chapters 1 and 2

Today's Topics

Introduction To Systems of First Order Differential Equations

Lotka – Volterra Predator Prey Model

$x(t)$ = Population of Prey

$y(t)$ = Population of Predator

$$x' = ax - bxy$$

$$y' = mxy - ny$$

where a, b, m, n are positive constants.

Richardson Arms Race Model

$x(t)$ = Arms Expenditure of Blue Nation

$y(t)$ = Arms Expenditure of Red Nation

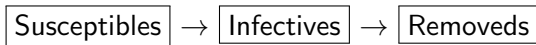
$$x' = ay - mx + r$$

$$y' = bx - ny + s$$

where a, b, m, n are positive constants while r and s are constants.

Kermack – McKendrick Epidemic Model

(1927 – 1939)



S = Number of Susceptibles

I = Number of Infectives

R = Number of Recovereds

$$S' = -\beta SI$$

$$I' = \beta SI - rI$$

$$R' = rI$$



Home Heating Model

$x(t)$ = Temperature of the Ground Floor

$y(t)$ = Temperature of Upper Floor

k = coefficient of thermal conductivity

k_1 = Thermal Conductivity of Floor on Ground Level

k_2 = Thermal Conductivity of Ceiling on Ground Level

k_3 = Thermal Conductivity of Walls on Ground Level

k_4 = Thermal Conductivity of Walls on Upper Floor and Roof

T_e = Temperature of Surrounding Environment

$$\begin{aligned}x' &= -(k_1 + k_2 + k_3)x + k_2y + k_1T_g + k_3T_e(t) + f(t) \\y' &= k_2x - (k_2 + k_4)y + k_4T_e(t)\end{aligned}$$

where $f(t)$ describes the heat source located on the ground floor.

Terrorism

x = Number of Terrorists at time t

y = Number of Individuals Who Can Be Influenced By Terrorist Propaganda and Counter – Terrorist Influence.

z = Number of Individuals Resistant To Terrorist Propaganda

$$x' = ay - bx^2 + (c - 1)$$

$$y' = -axy - cx^2y + fx + gy$$

$$z' = ex^2y - hx + mz$$

Our Focus: Linear Models

$$x' = a(t)x + b(t)y + f(t), y' = c(t)x + d(t)y + g(t)$$

Narrow Focus First to **Homogeneous Systems**

$$x' = a(t)x + b(t)y, y' = c(t)x + d(t)y$$

Initial Concern: **Homogeneous Systems of 2 First Order Differential Equations With Constant Coefficients**

$$x' = ax + by, y' = cx + dy$$

has form $\mathbf{X}' = A \mathbf{X}$ where $\mathbf{X} = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$

Ideas and Tools From Linear Algebra Are Essential To This Study

Initial Concern: **Homogeneous Systems of 2 First Order
Differential Equations With Constant Coefficients**

$$x' = ax + by, y' = cx + dy$$

$$\begin{bmatrix} x \\ y \end{bmatrix}' = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$
$$\mathbf{x}' = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mathbf{x}$$

**Ideas and Tools From Linear Algebra Are Essential To This
Study**

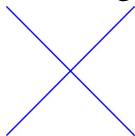
Start With System of Linear **ALGEBRAIC** Equations

Two Linear Equations in 2 Unknowns

$$3x + 4y = 18$$

$$5x - 2y = 4$$

Geometric Nature of Possible Solutions



1 Solution



No Solutions



Infinitely Many Solutions

Matrix Representation

$$\begin{bmatrix} 3 & 4 \\ 5 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 18 \\ 4 \end{bmatrix}$$

$A \quad \mathbf{X} = \mathbf{b}$

Reduce A to Row Echelon Form

Example

$$3x_1 + 5x_2 - 4x_3 = 0$$

$$-3x_1 - 2x_2 + 4x_3 = 0$$

$$6x_1 + x_2 - 8x_3 = 0$$

$$\left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ -3 & -2 & 4 & 0 \\ 6 & 1 & -8 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -4/3 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$x_2 = 0$$

$$x_1 = \frac{4}{3}x_3 \rightarrow x_3 = \frac{3}{4}x_1$$

$$\mathbf{X} = \begin{bmatrix} a \\ 0 \\ \frac{3}{4}a \end{bmatrix}, a \text{ any value}$$

One Dimensional Set of Solutions

EIGENVALUES AND EIGENVECTORS

A $n \times n$ [Square Matrix]

\vec{x} $n \times 1$ [Element of R^n]

Then $A\vec{x}$ is another vector in R^n .

Is there a **nonzero** vector \vec{v} and a constant λ such that

$$A\vec{v} = \lambda\vec{v}?$$

The equation $A\vec{v} = \lambda\vec{v}$ is equivalent to

$$A\vec{v} - \lambda\vec{v} = \vec{0}$$

$$\text{or } (A - \lambda I)\vec{v} = \vec{0}$$

which is a system of homogeneous equations.

The system has nontrivial solution if and only if

$(A - \lambda I)$ is Non-Invertible.

$$\Rightarrow \det(A - \lambda I) = 0.$$