## MATH 223: Multivariable Calculus



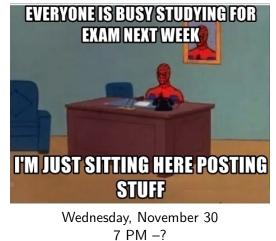
### Class 29: November 18, 2022

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## Notes on Assignment 26 Assignment 27 Weighted Curves and Surfaces of Revolution

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You May Bring One Sheet (Two-Sided) of Notes

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#### Today:

#### **Conservative Vector Fields and Conservation of Energy** Weighted Curves and Surfaces of Revolution

Monday, November 26: Normal Vectors and Curvature Following Wednesday: Flow Lines, Divergence and Curl

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#### INTEGRATION OF VECTOR FIELDS $\mathbf{F} : \mathbb{R}^n \to \mathbb{R}^n$

 $\mathbf{F}(\vec{x}) = (F_1(\vec{x}), F_2(\vec{x}), ..., F_n(\vec{x}))$ 

What is Meaning of  $\int_{\mathcal{D}} \mathbf{F}$ ?

For Now:  $\mathcal{D}$  is a one-dimensional set in  $\mathbb{R}^n$  $\mathcal{D}$  is a curve parametrized by a function  $g: \mathbb{R}^1 \to \mathbb{R}^n$  on an interval  $a \leq t \leq b$ We denote the image of g by  $\gamma$ Definition The Line Integral of **F** over  $\gamma$  is

$$\int_{\gamma} \mathbf{F} \cdot d\vec{x} = \int_{a}^{b} \mathbf{F}(g(t)) \cdot g'(t) \, dt$$

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<u>Theorem</u> The value of the line integral  $\int_{\gamma} \mathbf{F}$  is independent of the parametrization of  $\gamma$  but in general is dependent on the curve itself.

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# For some vector fields, the line integral $\int_{\gamma} \mathbf{F}$ depends only on the endpoints of the curve. In particular, this is true of $\mathbf{F}$ is a gradient field; that is,

$$\mathbf{F} = \nabla f$$

for some real-valued function f.

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Theorem (The Fundamental Theorem of Calculus for Line Integrals. Let  $f : \mathbb{R}^n \to \mathbb{R}^1$  be continuously differentiable and let  $\mathbf{F} = \nabla f$  and suppose  $\gamma : \mathbb{R}^1 \to \mathbb{R}^n$  is a continuous curve with endpoints  $\vec{a}$ and  $\vec{b}$ . Then  $\int_{\gamma} \mathbf{F} = \int_{\gamma} \nabla f = f(\vec{b}) - f(\vec{a}).$ 

If  $\mathbf{F} = \nabla f$  for some f, then we call  $\mathbf{F}$ a **Conservative Vector Field** or an **Exact Vector Field** 

and f is called a **Potential** of **F** 

The function  $P(\vec{x}) = -f(\vec{x})$  is the **Potential Energy** of the field **F**.

Conservative Vector Field:  $\mathbf{F}(x, y) = (2xy, x^2 + 2y)$ Nonconservative Example  $\mathbf{F}(x, y) = (x, x + 1)$ 

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#### Application: Conservation of Energy

Suppose  $\mathbf{g}(t)$  represents the position of an object of varying mass m(t) in space at time t.

The velocity vector of the object is  $\mathbf{v} = \mathbf{g}'(t)$ . The Force acting on the object at position g(t) is

$$\mathbf{F}(\mathbf{g}(t)) = [m(t)\mathbf{v}(t)]' = m'(t)\mathbf{v}(t) + m(t)\mathbf{v}'(t)$$

#### Then

$$\begin{aligned} \mathbf{F}(\mathbf{g}(t)) \cdot \mathbf{g}'(t) &= \mathbf{F}(\mathbf{g}(t)) \cdot \mathbf{v}(t) \\ &= \left[ m'(t)\mathbf{v}(t) + m(t)\mathbf{v}'(t) \right] \cdot \mathbf{v}(t) \\ &= m'(t)\mathbf{v}(t) \cdot \mathbf{v}(t) + m(t)\mathbf{v}'(t) \cdot \mathbf{v}(t) \\ &= m'(t)s^2(t) + m(t)s'(t)s(t) \end{aligned}$$

where  $s(t) = |\mathbf{v}(t)| = \mathbf{speed}$  at time t.

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To Show: 
$$s'(t)s(t) = \mathbf{v}'(t) \cdot \mathbf{v}(t)$$
  
Start with  $s^2(t) = |\mathbf{v}(t)|^2 = \mathbf{v}(t) \cdot \mathbf{v}(t)$ 

Differentiate each side with respect to t:

$$\begin{split} 2s(t)s'(t) &= \mathbf{v}'(t)\cdot\mathbf{v}(t) + \mathbf{v}(t)\cdot\mathbf{v}'(t) = 2\mathbf{v}'(t)\cdot\mathbf{v}(t)\\ & \text{Thus } s'(t)s(t) = \mathbf{v}'(t)\cdot\mathbf{v}(t)\\ & \text{and} \end{split}$$

$$\mathbf{F}(\mathbf{g}(t)) \cdot \mathbf{g}'(t) = m'(t)s^2(t) + m(t)s'(t)s(t)$$

#### Application: Conservation of Energy

(a) 
$$\mathbf{F}(\mathbf{g}(t)) \cdot \mathbf{g}'(t) = m'(t)s^2(t) + m(t)s'(t)s(t)$$
  
We'll use the scalar  $v$  for the scalar  $s$   
so  $\mathbf{F}(\mathbf{g}(t)) \cdot \mathbf{g}'(t) = m'(t)v^2(t) + m(t)v'(t)v(t)$ 

(b) 
$$m(t) = \text{Constant implies } m' = 0$$
  
so  $\mathbf{F}(g(t)) \cdot g'(t) = mv(t)v'(t)$ 

$$\int_{a}^{b} mv(t)v'(t) \, dt = \frac{mv(t)^{2}}{2} \Big|_{t=a}^{t=b}$$

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#### Application: Conservation of Energy

Suppose **F** is a force field which moves an object of mass m from  $\vec{a}$  to  $\vec{b}$  along curve  $\gamma$ .

Let g be a parametrization of curve  $\gamma$  and v(t) = g'(t). Then the work done in moving the object is

$$rac{1}{2}m|v(t_b)|^2-rac{1}{2}m|v(t_a)|^2$$
 ( Change in Kinetic Energy)

If **F** is a conservative field, then we can also compute work done by  $\int_{\gamma} \mathbf{F} = f(\vec{b}) - f(\vec{a}) = p(\vec{a}) - p(\vec{b}) =$ Change in Potential Energy Equating the two expressions for work, we have  $\frac{1}{2}m|v(t_b)|^2 - \frac{1}{2}m|v(t_a)|^2 = p(\vec{a}) - p(\vec{b})$   $p(\vec{b}) + \frac{1}{2}m|v(t_b)|^2 = p(\vec{a}) + \frac{1}{2}m|v(t_a)|^2$ where  $\vec{a}$  and  $\vec{b}$  are any 2 points So Sum of Potential and Kinetic Energy is Constant Law of Conservation of Total Energy

#### Arc Length

Let  $q: \mathbb{R}^1 \to \mathbb{R}^n$  be defined on  $a \leq t \leq b$ . Then the image of g is a curve  $\gamma$  with length  $L(\gamma) = \int_{a}^{b} |g'(t)| dt$ . Example: Cycloid:  $g(t) = (t - \sin t, 1 - \cos t), 0 \le t \le 2\pi$ 3 , 2  $\frac{\pi}{4}$   $\frac{\pi}{2}$   $\frac{3\pi}{4}$   $\pi$   $\frac{5\pi}{4}$   $\frac{3\pi}{2}$   $\frac{7\pi}{4}$   $2\pi$  $q'(t) = (1 - \cos t, \sin t)$  $|q'(t)| = \sqrt{(1 - \cos t)^2 + \sin^2 t} = \sqrt{1 - 2\cos t + \cos^2 t + \sin^2 t} =$  $\sqrt{2 - 2\cos t} = \sqrt{2(1 - \cos t)} = \sqrt{2(2\sin^2(t/2))} = 2\sin(t/2)$  $L(\gamma) = \int_0^{2\pi} 2\sin(t/2) dt = -4\cos(t/2) \Big|^{2\pi} = 8$ 

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#### **Other Formulations**

$$L(\gamma) = \int_{a}^{b} |g'(t)| dt$$

If a curve is given by  $y = f(x), a \le x \le b$ , then let g(t) = (t, f(t))so  $|g'(t)| = |(1, f'(t)| = \sqrt{1 + [f'(t)]^2}$ If  $g(t) = (h_1(t), h_2(t))|$ , then  $|g'(t)| = \sqrt{[h'_1]^2 + [h'_2]^2}$ .

#### **Arc Length Parametrization**

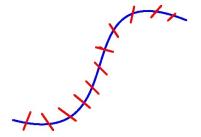
Let  $\gamma$  be a curve parametrized by g(t) for  $t_0 \le t \le t_1$ With  $\vec{x}(t) = g(t), \vec{x}$  is position at time t.

Then arc length function is  $s = s(t) = \int_{t_0}^t |g'(t)| dt = \int_{t_0}^t |x(t)| dt$ If |g'(t)| = 1 for all t, then we say the curve is parametrized by arc length

Moving along the curve with uniform speed of 1 means that at time s we are at a point s units along the curve.

Example 1: Unit Circle: 
$$g(t) = (\cos t, \sin t), 0 \le t \le 2\pi$$
  
Example 2 Helix:  $g(t) = \left(\frac{a \cos t}{\sqrt{a^2+b^2}}, \frac{a \sin t}{\sqrt{a^2+b^2}}, \frac{bt}{\sqrt{a^2+b^2}}\right)$ .  
Then  $g'(t) = \left(\frac{-a \sin t}{\sqrt{a^2+b^2}}, \frac{a \cos t}{\sqrt{a^2+b^2}}, \frac{b}{\sqrt{a^2+b^2}}\right)$ .  
and  $|g'(t)| = \sqrt{\frac{a^2 \sin^2 t + a^2 \cos^2 t + b^2}{a^2+b^2}} = \sqrt{\frac{a^2+b^2}{a^2+b^2}} = 1$ 

Mass of a Weighted Curve Density  $(\mu)$  is mass per unit length



Total Mass  $\sim \sum \mu(point) \times$  Length of short piece of curve

Total Mass =  $\int \mu(g(t)) |g'(t)| dt$ 

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Total Mass : 
$$\int \mu(g(t))|g'(t)| dt$$
  
Example Spacecurve  $g(t) = (\sin t, \cos t, t^2), 0 \le t \le 2\pi$   
Here  $g'(t) = (\cos t, -\sin t, 2t)$   
so  $|g'(t)| = \sqrt{\cos^2 t + \sin^2 t + 4t^2} = \sqrt{1 + 4t^2}$   
 $\int_{0}^{0} \int_{0}^{0} \int_{0}$ 

#### **Surface of Revolution**

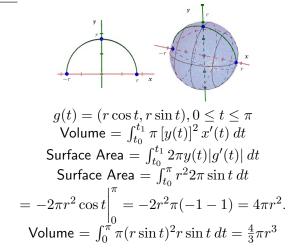
S is a surface in  $\mathbb{R}^3$  obtained by rotating a plane curve about a straight line in the plane. Simplest Case: Rotate y = f(x) about x-axis. У y = f(x)h x 0 а ds Volume =  $\int_{a}^{b} \pi [f(x)]^{2} dx$ Surface Area =  $\int_{a}^{b} 2\pi \sqrt{1 + [f(x)]^2} dx$ 

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$$\begin{aligned} \mathsf{Volume} &= \int_a^b \pi \left[ f(x) \right]^2 \, dx \\ \mathsf{Surface} \; \mathsf{Area} &= \int_a^b 2\pi \sqrt{1 + \left[ f(x) \right]^2} \, dx \\ \mathsf{Suppose} \; \mathsf{curve} \; \mathsf{has} \; \mathsf{parametrization} \; g: \mathbb{R}^1 \to \mathbb{R}^2, t_0 \leq t \leq t_1 \\ g(t) &= (x(t), y(t)) \; \mathsf{with} \; g(t_0) = (a, f(a)) \; \mathsf{and} \; g(t_1) = (b, f(b)). \\ \mathsf{Volume} &= \int_{t_0}^{t_1} \pi \left[ y(t) \right]^2 x'(t) \, dt \\ \mathsf{Surface} \; \mathsf{Area} &= \int_{t_0}^{t_1} 2\pi y(t) |g'(t)| \, dt \end{aligned}$$

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Example Revolve Semicircle of radius r about horizontal axis.



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